
Ros note Documentation

Release

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ROS

1.1 IMU

(Inertial measurement unit)

1.2 pcl

1.2.1

```
$ rosrun pcl_ros pointcloud_to_pcd input:=/velodyne/pointcloud2
```


2.1 ROS

ROS

- [\[\[https://www.shiyanlou.com/courses/?tag=ROS\]\]](https://www.shiyanlou.com/courses/?tag=ROS)
- [\[\[https://www.ncnynl.com/archives/201608/496.html\]\]](https://www.ncnynl.com/archives/201608/496.html)

2.2

- [\[\[https://www.ncnynl.com/archives/201610/947.html\]\]](https://www.ncnynl.com/archives/201610/947.html) `Moveit`

2.3

- [\[\[https://www.ncnynl.com/archives/201611/1095.html\]\]](https://www.ncnynl.com/archives/201611/1095.html) `Rplidar SLAM`

CHAPTER 3

http://docs.ros.org/api/sensor_msgs/html/msg/PointCloud2.html

CHAPTER 4

tips

Use `catkin build` instead of `catkin_make`

CHAPTER 5

Indices and tables

- `genindex`
- `modindex`
- `search`